

Construction of Cascaded Traffic Sign Detector Using Generative Learning

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Abstract

We propose a method for construction of a cascaded traffic sign detector. Viola et al. have proposed a robust and extremely rapid object detection method based on a boosted cascade of simple feature classifiers. To obtain a high detection accuracy in real environment, it is necessary to train the classifier with a set of learning images which contain various appearances of detection targets. However, collecting the traffic sign images manually for training takes much cost. Therefore, we use a generative learning method for constructing the traffic sign detector. In this paper, shape, texture and color changes are considered in the generative learning. By this method, the performance of the traffic sign detection improves and the cost of collecting the training images is reduced at the same time. Experimental results using car-mounted camera images showed the effectiveness of the proposed method.

1. Introduction

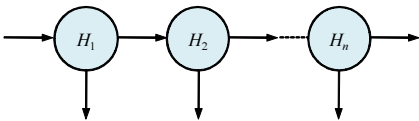


Figure 1. Architecture of a classifier-cascade.

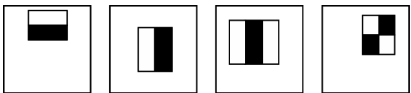


Figure 2. Examples of Haar-like features.

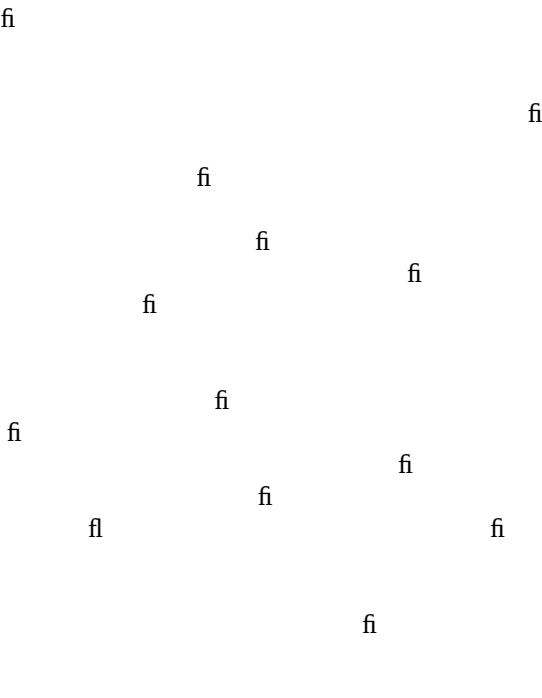
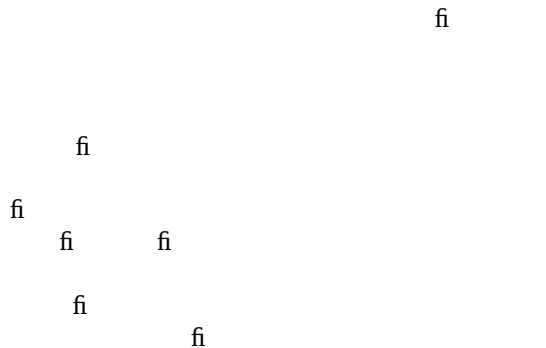




Figure 3. Examples of Japanese traffic signs captured in various conditions. These captured images contain various changes on shape, texture and color, such as 3D-rotation, stretching, optical blurring, background pattern, discoloration and reflection.

2. Construction of cascaded traffic sign detector using generative learning



2.1. Modeling shape, texture and color changes

fi

- Shape and texture change models

Rotation :

$$x \quad y \quad z$$

Shifting :

$$\Delta \quad \Delta$$

Stretching :

$$w \quad h$$

Optical blurring :

$$\left(\begin{array}{c} \mu \\ \sigma^2 \end{array} \right) = \frac{1}{2} \exp \left(-\frac{\mu^2 + \sigma^2}{2} \right)$$

Background pattern :

- Color change models

Discoloration :

$$\left(\begin{array}{c} i \\ i \\ i \end{array} \right)$$

Reflection and shadow :

fi

fi

2.2. Generation of traffic sign images

$$\left(\begin{array}{c} x \quad y \quad z \quad \Delta \quad \Delta \quad b \quad i \quad i \quad i \end{array} \right) P =$$

fi

2.3. Construction of a cascaded traffic sign detector

$$\left(\begin{array}{c} fi \\ fi \end{array} \right) \quad fi$$

fi

fi

-
- = = = + +
- = 0.2989 + 0.5866 + 0.1145



Figure 4. Examples of the generated traffic sign images. In the experiments, detection targets are these twenty kinds of round regulatory signs.

3. Experiments

3.1. Conditions

640 × 480

μ

σ

3.2. Methods

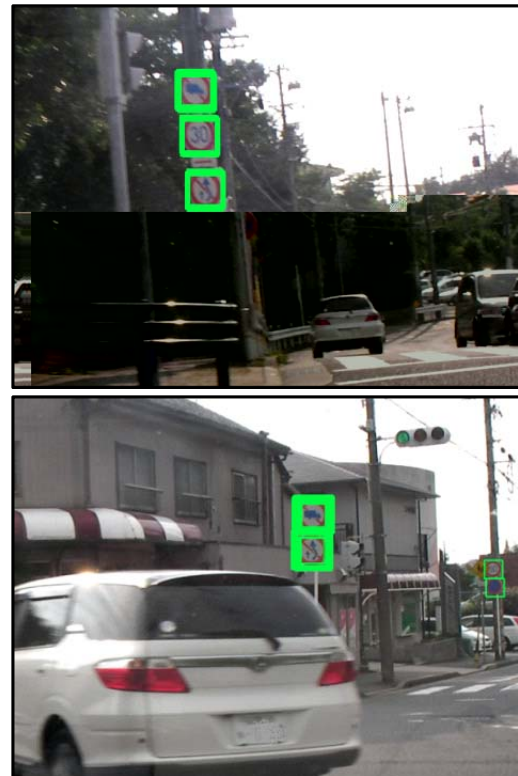
4. Conclusion

Table 1. Mean and standard deviation of generation parameters.

	Shape and texture models								Color models						
	Rotation °			Shifting		Stretching		Optical blurring	Discoloration						Reflection & shadow
									Red region			Blue region			
	θ_x	θ_y	θ_z	Δx	Δy	w	h	σ	h_r	s_r	v_r	h_b	s_b	v_b	v
μ															-0.25
σ															

Table 2. Comparison of detection ability.

		0.97
		0.93
		0.95



Acknowledgments :

References

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International Conference on Intelligent Transportation Sys-
tems*

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Figure 5. Examples of the detection results. Each rectangle represents detected traf c sign.